



第3回

International Session Best  
Presentation Award



**第3回**

**International Session Best  
Presentation Award  
Finalists**



The Robotics Society of Japan  
2021

International Session Best Presentation Award Finalist

is presented to

**Hao Chen**

for the presentation entitled

**Vision-Based Novel Object Grasping based on Object-Association  
Matching with Grasp Database**

presented at the 39<sup>th</sup> Annual Conference of the Robotics Society of Japan

10<sup>th</sup> September 2021

Kimitoshi Yamazaki  
General Chair  
The 39<sup>th</sup> Annual Conference  
of the Robotics Society of Japan



The Robotics Society of Japan  
2021

International Session Best Presentation Award Finalist

is presented to

**Koen Hertenberg**

for the presentation entitled

**Telepresence Robot System Operated by a Cycling Wheelchair**

presented at the 39<sup>th</sup> Annual Conference of the Robotics Society of Japan

10<sup>th</sup> September 2021

Kimitoshi Yamazaki

General Chair

The 39<sup>th</sup> Annual Conference  
of the Robotics Society of Japan



The Robotics Society of Japan  
2021

International Session Best Presentation Award Finalist

is presented to

**Yan Wang**

for the presentation entitled

**An Adaptive LfD Framework for Complex Robotic Assembly Tasks**

presented at the 39<sup>th</sup> Annual Conference of the Robotics Society of Japan

10<sup>th</sup> September 2021

Kimitoshi Yamazaki  
General Chair  
The 39<sup>th</sup> Annual Conference  
of the Robotics Society of Japan



第3回

International Session Best  
Presentation Award  
Winner



The Robotics Society of Japan  
2021

## International Session Best Presentation Award

is presented to

**Koen Hertenberg**

for the presentation entitled

**Telepresence Robot System Operated by a Cycling Wheelchair**

presented at the 39<sup>th</sup> Annual Conference of the Robotics Society of Japan

10<sup>th</sup> September 2021

Kimitoshi Yamazaki

General Chair

The 39<sup>th</sup> Annual Conference  
of the Robotics Society of Japan